# A new stationary radio-echo sounding system for cryospheric studies: instrument, first results, and perspectives

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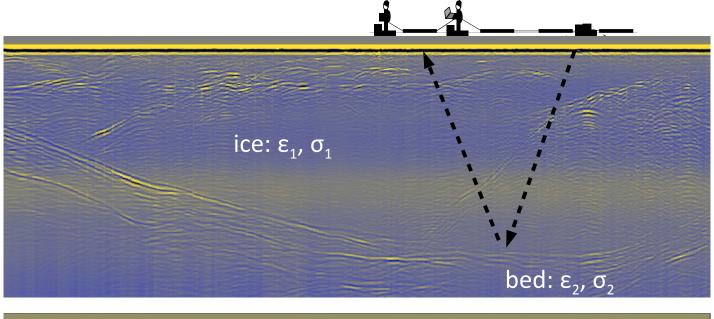
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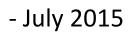
# Principles of ice-penetrating radar

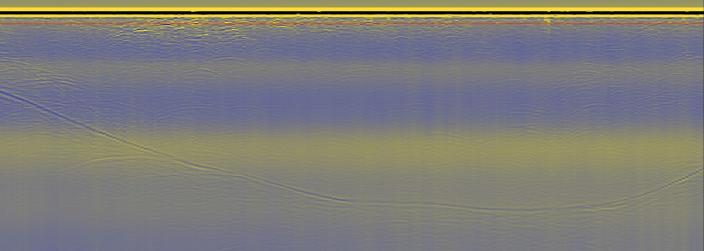
Ice is nearly transparent to radio waves in the MHz range



Same transect acquired in :

- July 2014





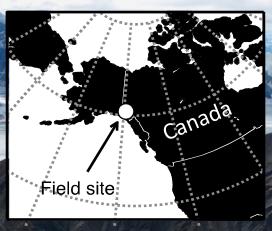
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#### 2014 - 2015 Deployment goals and location

Mt. Vancouver (4812m)

# Kaskawulsh Glacier



60°N

40°N

160°W 140°W 120°W

Radar system

Submerged pressure transducer

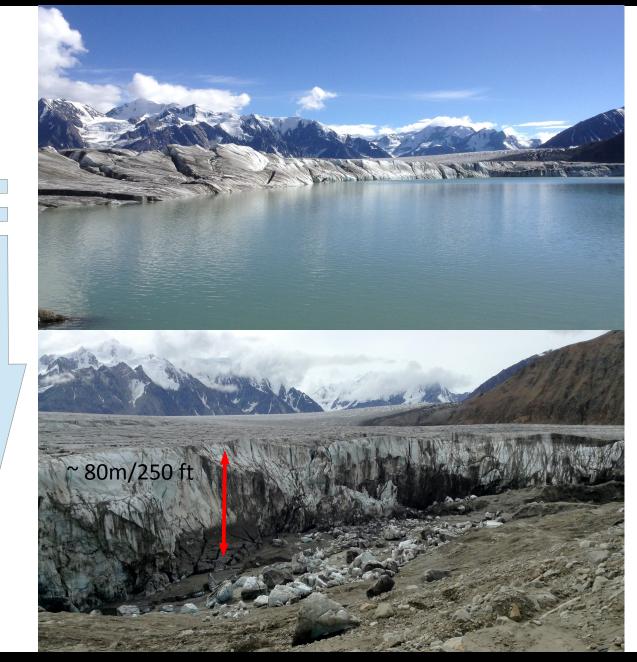
- Detection of englacial / subglacial temporal changes
- 2014 Pilot: Autonomous operation: 26 July 7 September 2014
- 2015 Pilot: Autonomous operation: 15 Jul 1 September 2015

Photo: Flavien Beaud

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# Motivation for system development



~24 hrs

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#### Stationary radar system deployment



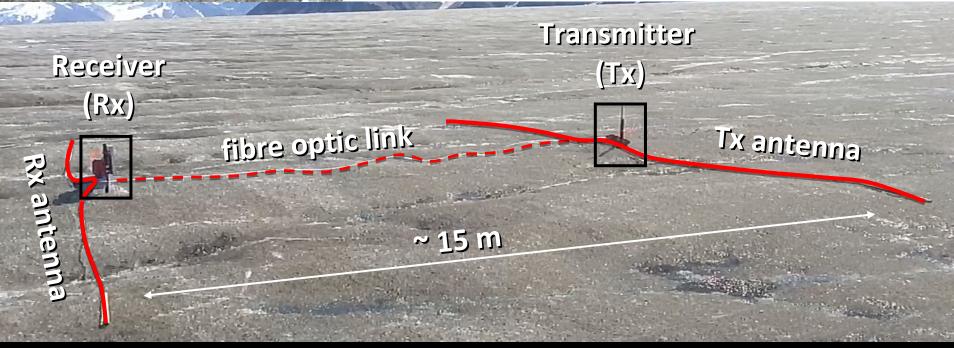
Dual channel input at 125 MS/s,

1024 Stacks,

Meas. Interval 4hrs (2014); 3hrs (2015)

Software for autonomous operation:

- Adaptive trigger level
- Auto-shutdown, and boot sequences
- Deployment and health check
- No user interface



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#### Stationary radar system design: transmitting unit

200g, ~ 2W power draw (active) 15mW sleeping (\*)



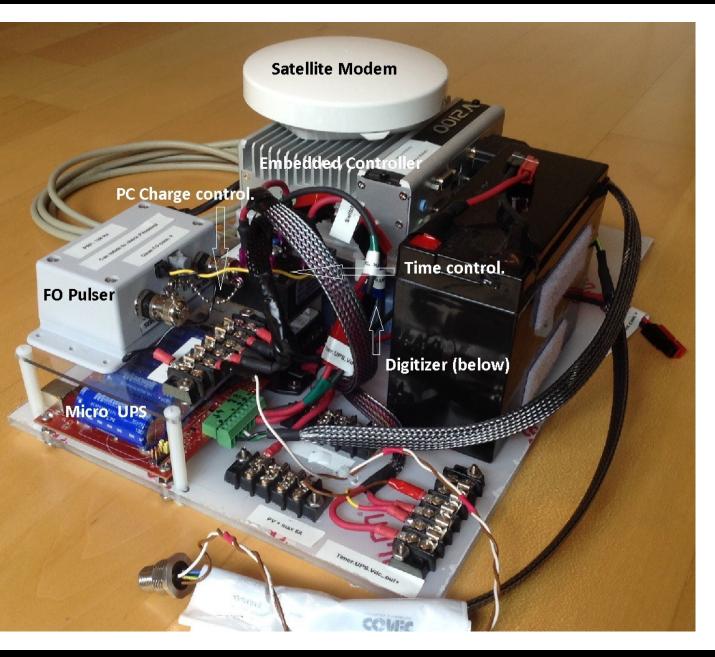
FO Input

# Adjustable pulse rate frequency (PRF): 512 Hz to 32 Hz

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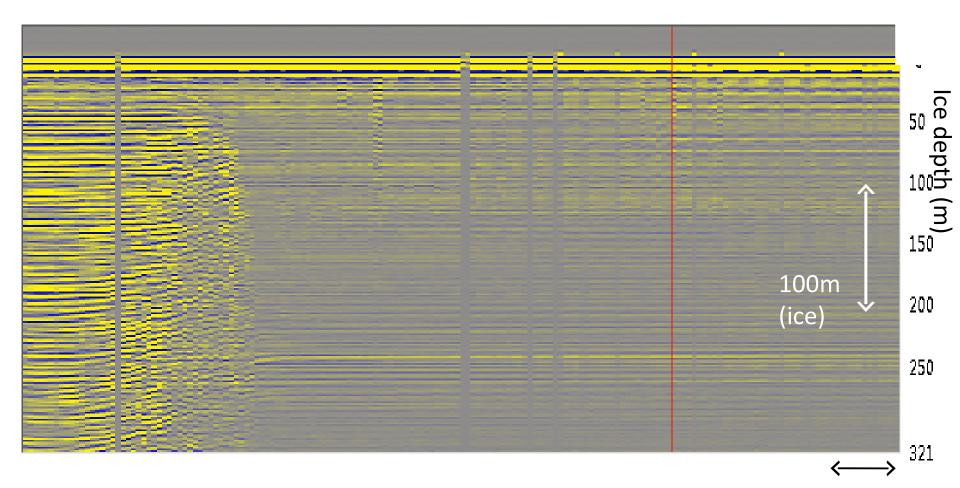
#### Stationary radar system design: receiving unit



- Based on previously developed roving radar (Mingo, Flowers, 2010)
- Compact, light
- ~ 7W operating
- ~ 4mW sleeping
- 1<sup>st</sup> Deployment:
- No sat com
- No Micro-UPS

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#### 2014 Deployment results – Temporal Radargram



- Zone with strong englacial reflectors
- Zone with "chaotic" reflectors
- Zone with weak englacial reflectors

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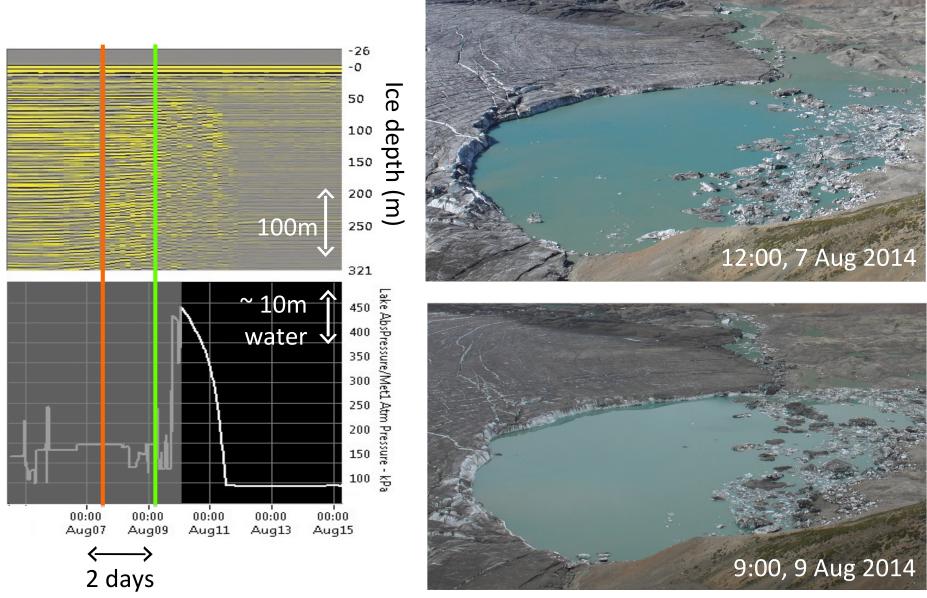
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Changes at the bed

2 days

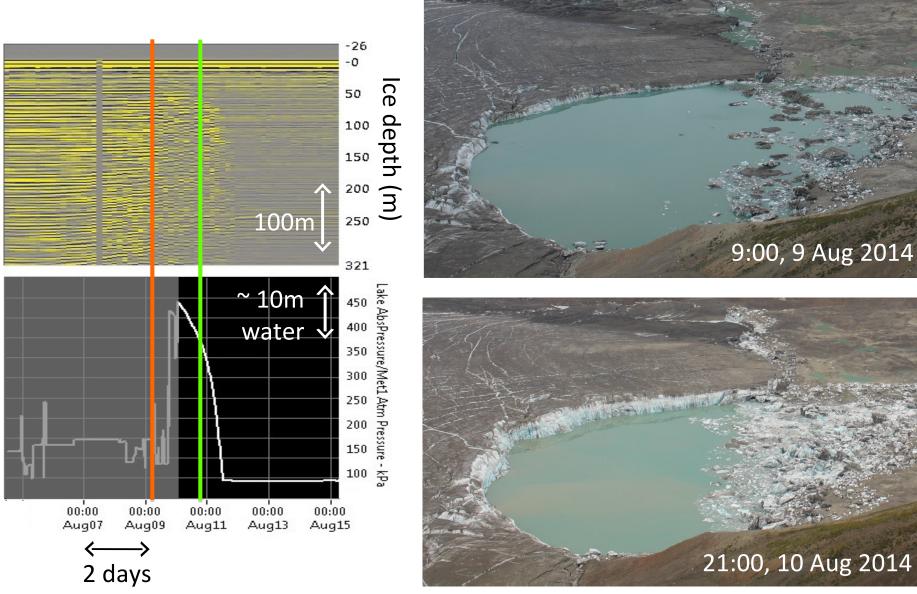
#### 2014 Deployment results



Images courtesy of Christian Schoof and UBC Glaciology

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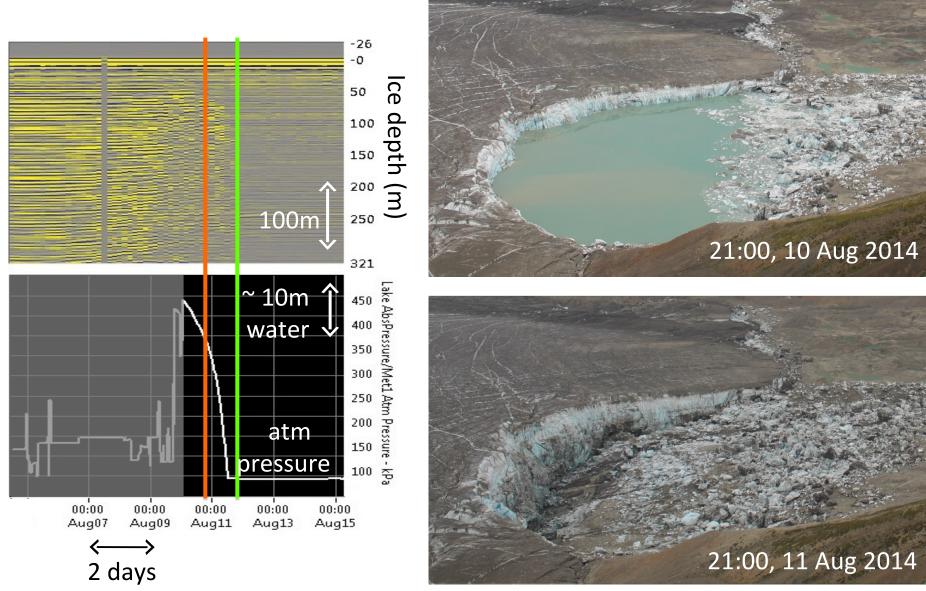
#### 2014 Deployment results



Images courtesy of Christian Schoof and UBC Glaciology

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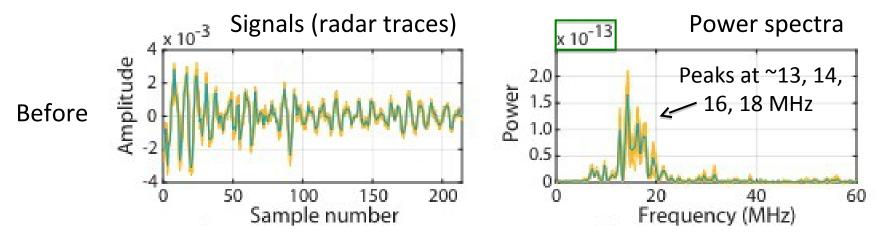
#### 2014 Deployment results



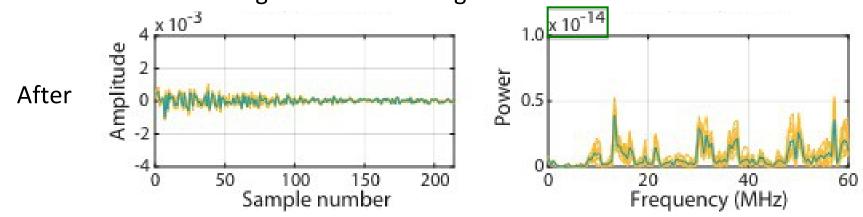
Images courtesy of Christian Schoof and UBC Glaciology

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#### Interpretation

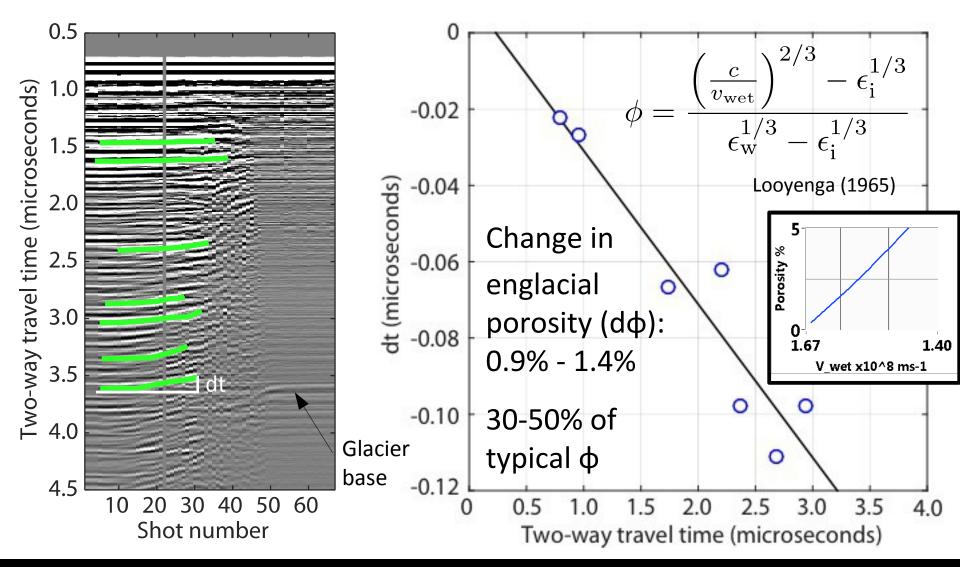


- Strong internal reflectors before drainage consistent with englacial water storage
- Transition from Strong to Weak englacial reflectors consistent with de-watering
- Spectral peaks correspond to water-filled void apertures of ~0.4 to 0.6 m (Jacobel and Raymond, 1984)
- Other evidence of englacial water storage and release?



# Interpretation: englacial porosity?

Decreasing englacial saturation during flood expressed as upturn in reflectors? Changes in wavespeed propagation used to estimate bulk porosity:



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# Ice Island Deployment



Project Collaborators: Anna Crawford, Derek Mueller, Greg Crocker. WIRL at Carleton University, Ottawa WATER & ICE RESEARCH LAB



- 14 sq.km Petermann II A-1-f, off Baffin Island- WIRL: Ice island deterioration modeling project
- II deterioration poses risk to off-shore infrastructure and shipping industry

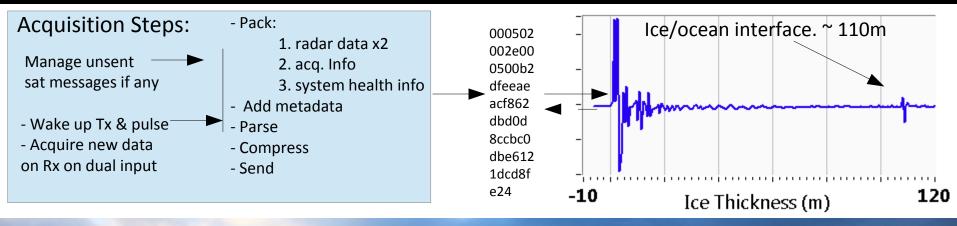
Photo : Gabriel Joyal

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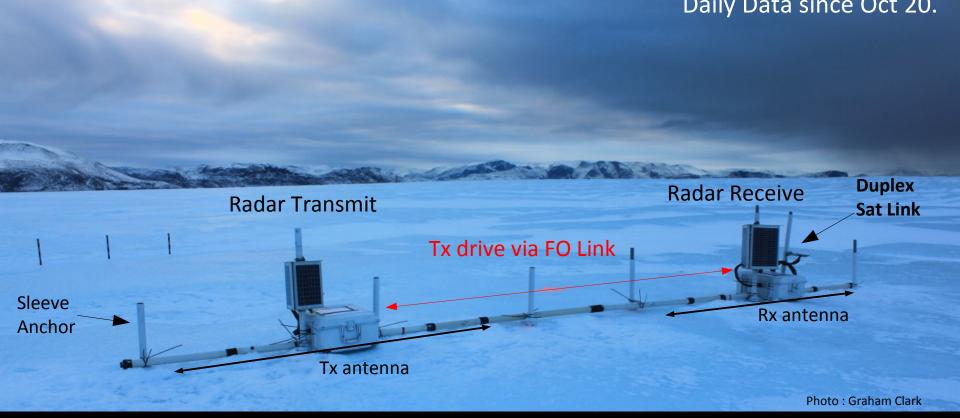
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#### Stationary Radar on Petermann II – A- 1-f

# Daily Data since Oct 20.



Daily Data since Oct 20.



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#### Summary

- Successful operation of a stationary radar system during two 7-week deployments
- First jökulhlaup event captured with autonomous radar system from 2014 dataset
- On-going ice island deployment



Future work:

Pursue application to ice-islands,

Extend application to subglacial geothermal areas

Phase sensitive radar. Other ideas ?

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AOOSM 2015

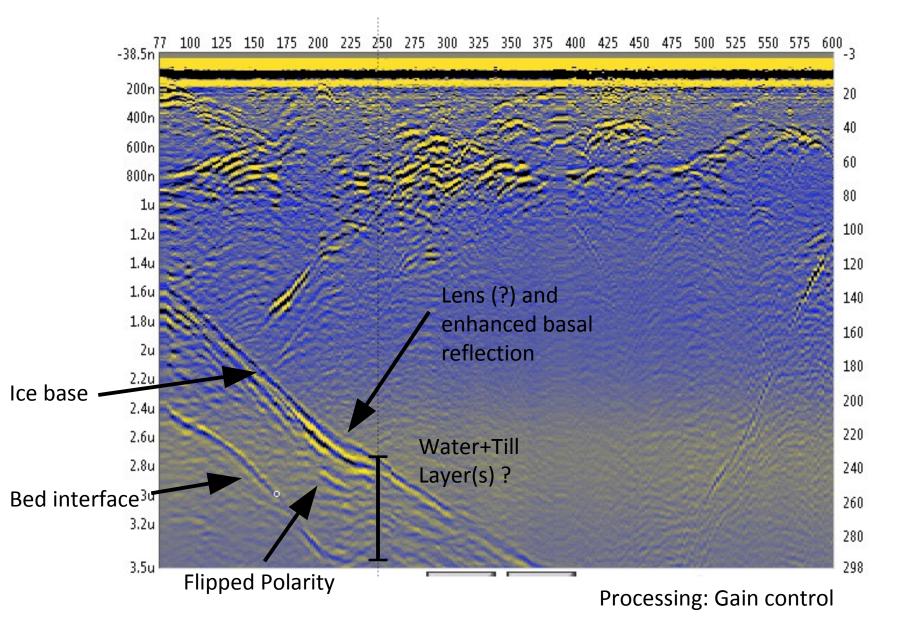


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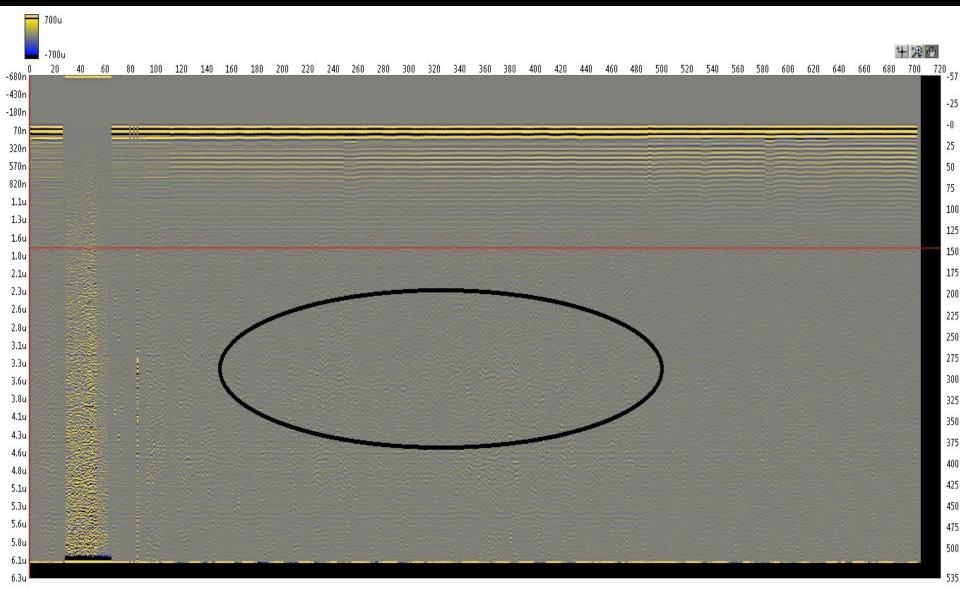
#### Location of Stationary system on Transect



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#### 2015 Kaskawulsh Data Set



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Previous work using impulse (\*) ice-penetrating radar for temporal studies

	Jacobel & Raymond (1984)	Jones (1987)	Gades et al. (1998)	Kulessa et al. (2008)
Time span	3 weeks	3 days	Several weeks	10 hours
Glacier, type	Variegated, temperate	Trapridge, polythermal	Variegated, temperate	Alps, likely polythermal
System	3Mhz, tape recorder	8MHz, first automated recording	3-5 MHz, automated recording	50MHz, automated recording
Meas. interval	A few hours	20 minutes	1 hour	10 minutes
Auto- nomous?	No	No	No	No
Current draw	A few A @ 12V	~ 2A @ 12V	A few A @ 12V	~ 3A @ 12V

(\*): FMCW Phase Sensitive radar: Brennan & Al (2013) , University College London & BAS: Autonomous system. Center Freq 300 Mhz.

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